

Toward an Innovative and SENSEable City

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sense*able* city lab:.::



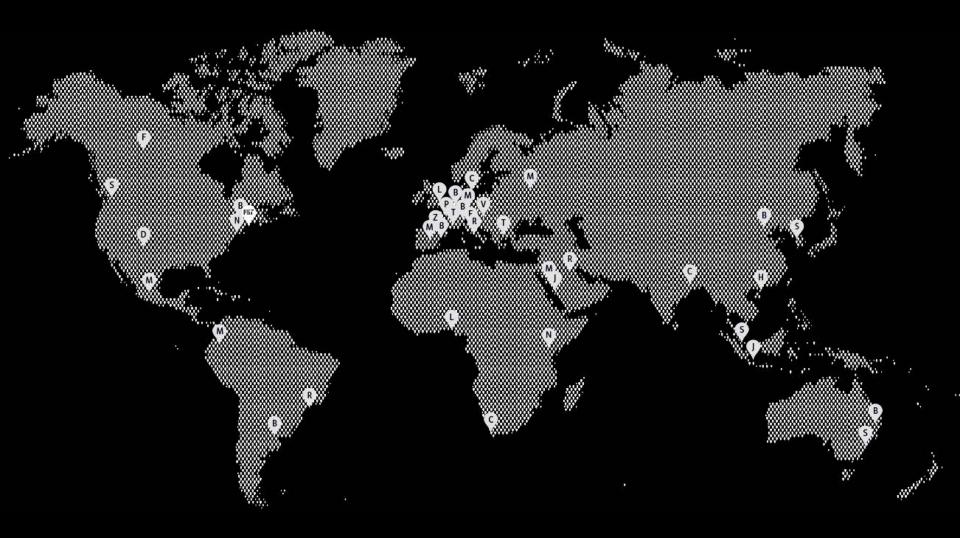


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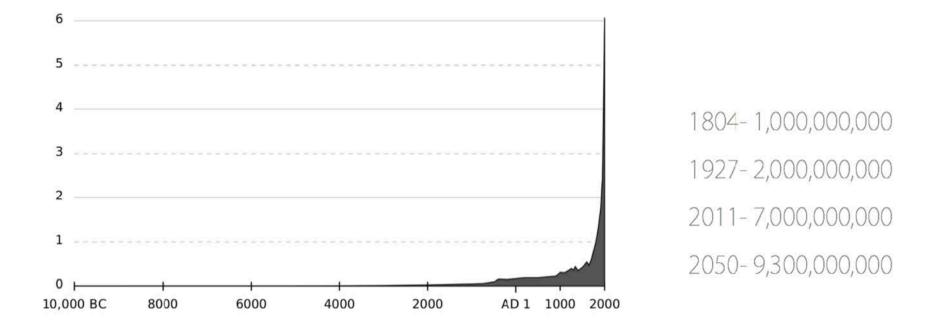
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senseable city lab:..: Massachusett



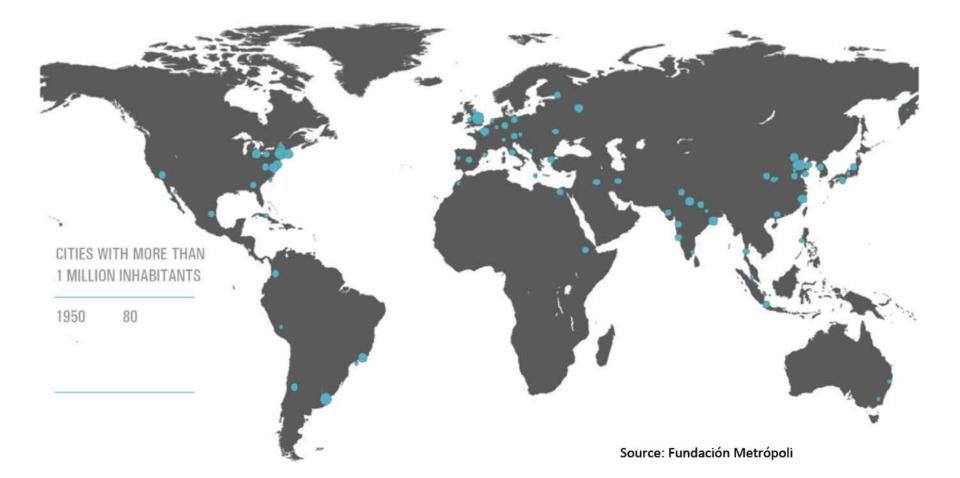
just a bit of context...

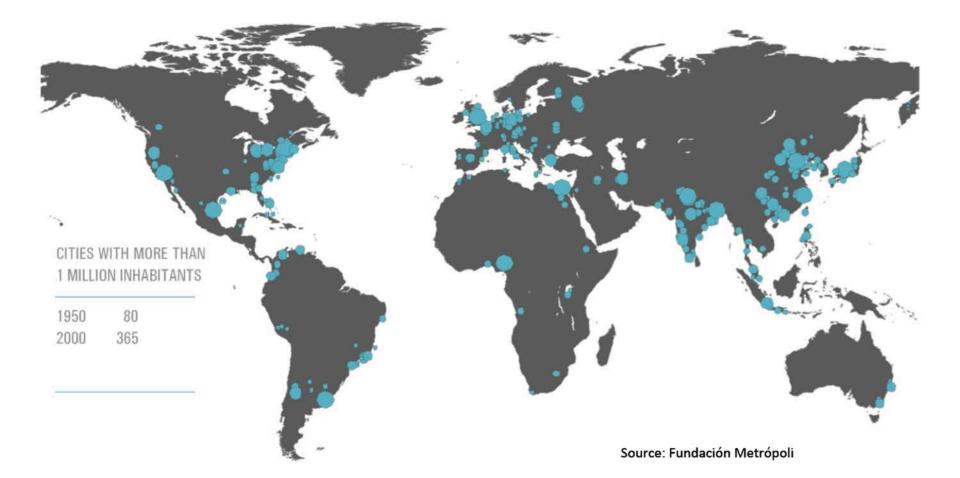


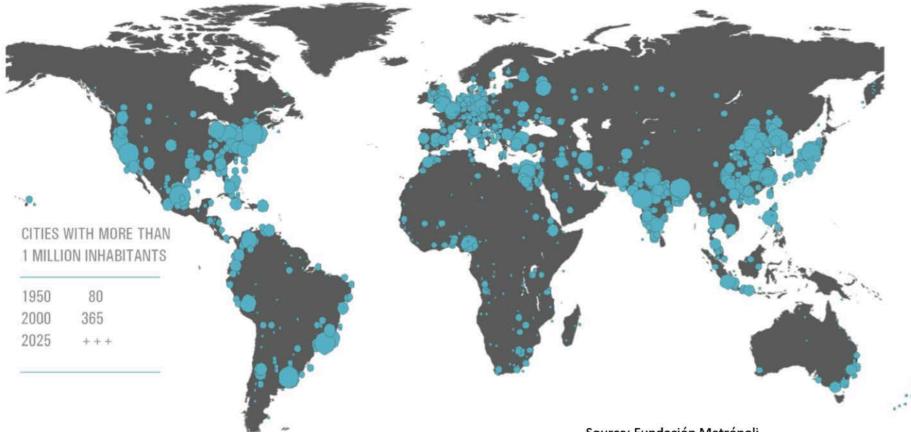
just a bit of context...

<u>1900</u> <u>2011</u> <u>2050</u> .23 BN 3.6 BN 6.3 BN

Source: UN World Urbanization Prospects 2012

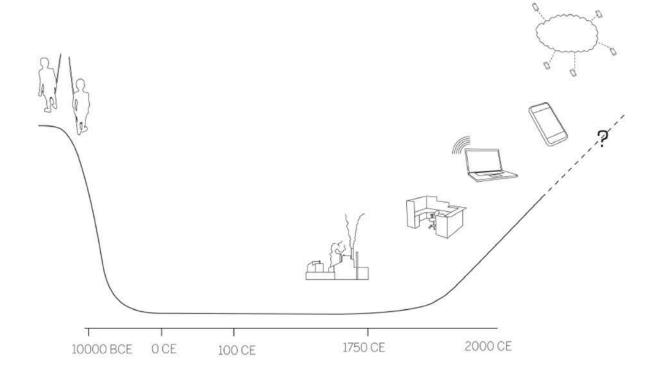


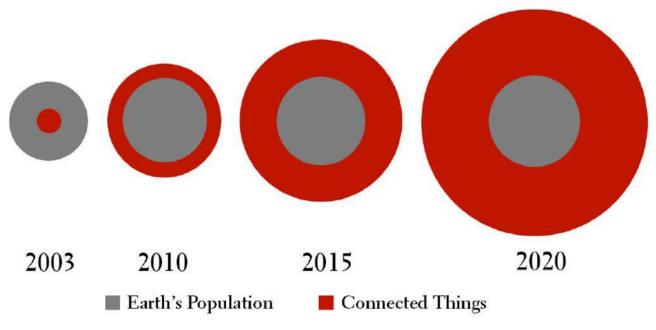




Source: Fundación Metrópoli

digital nomadism





Source: Cisco Systems



when things talk back.

trash track seattle + nyc, usa





-



_television set



_book shelf



_children's shoe



_blender



_mattress



_keyboard



_cardboard box



_motor oil / glove



_leather case



_dvd player



_phone book



_computer



_jeans



_tire

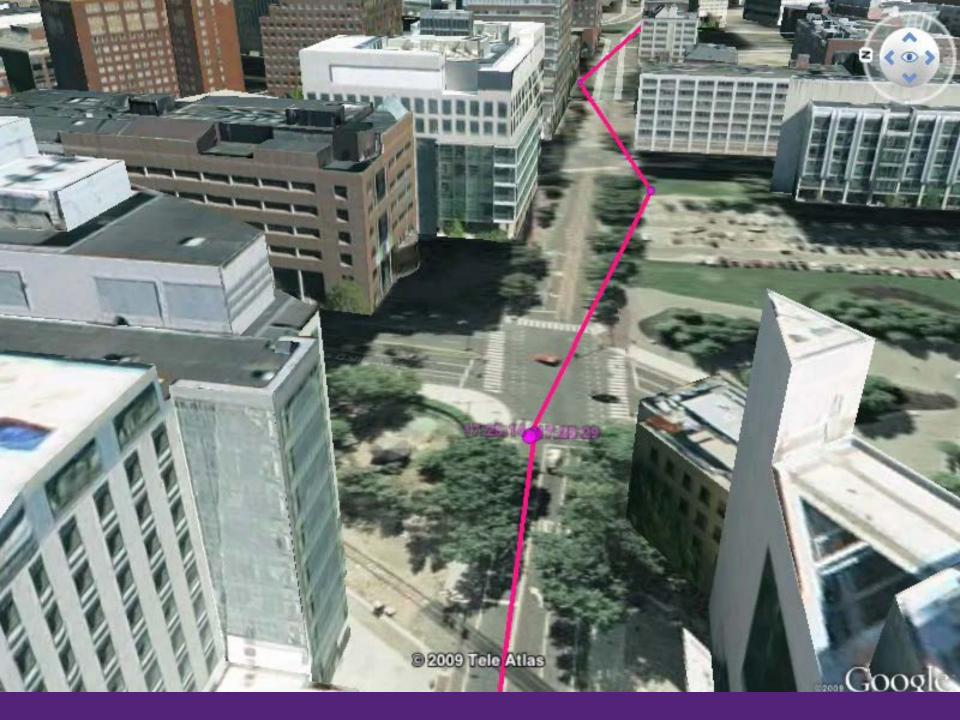




_porcelain soup bowl







How does e-waste travel across the world after disposal?

Sensors (with GPS and SMS)

Sleep mode: sensors wake up once per day battery lasts more than 2 years

200 devices tracked in the U.S. (CRT, LCD, printers)

MONITOUR E-TRASH TRANSPARENCY

by Device Type



by Starting Region



by Ending Region

Inside of US 138 Outside of US 62

Highlights

LCD from Waukegan, IL LCD from Cadillac, MI LCD from Wapakoneta, OH LCD from Oxford, MI LCD from Willard, OH LCD from Orlando, FL CRT from Youngstown, OH CRT from Norcross, GA CRT from Doraville, GA

200 Trackers

4 km Average Travel Distance

O days Average Active Time

Starting cities Ending cities Traveling paths Selected paths FILTER ABOUT

The second

SATELLITE STREET

•

CONTENTS ABOUT

LCD FROM WAUKEGAN, IL

Tracker ID 351564053163523 Travel Distance 14,579 km Travel Duration 71 days

STOP 07

CASTLE PEAK ROAD

City Ping Shan Coordinate 114.002787 | 22.436384 Date Sat Jan 10 2015 21:29:26

Media Content

Stop 7



Abandoned gaylord boxes filled with various electronics. Previous business owners had moved out and left this material behind. BAN's tracker had reported here about 10 months earlier.







Taiwan

Hong Kong

Malaysia



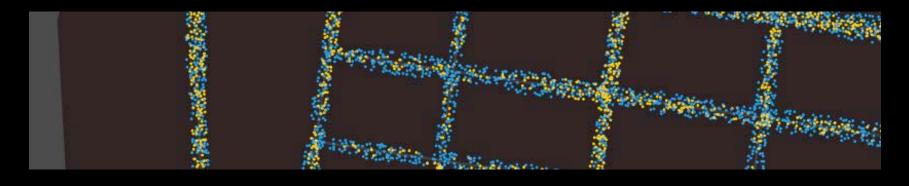
hubcab





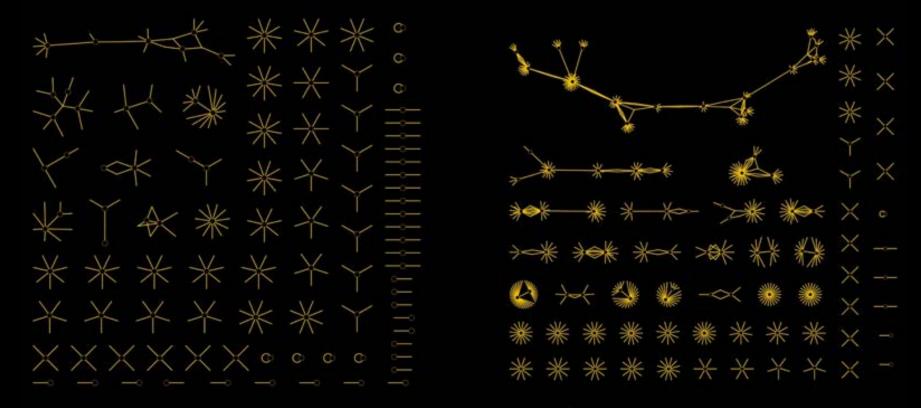








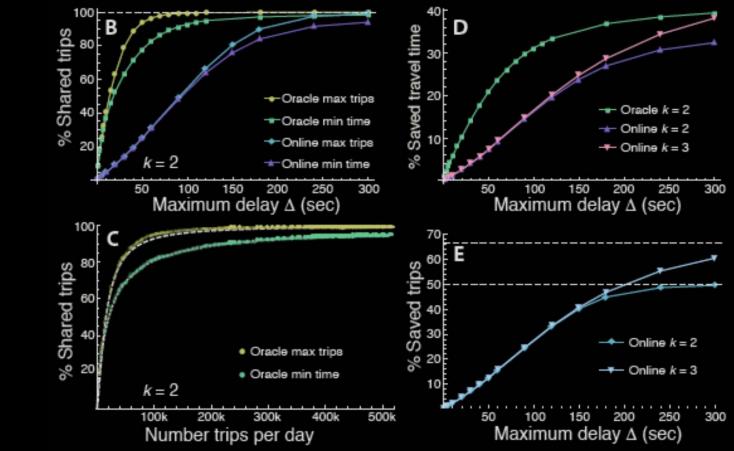


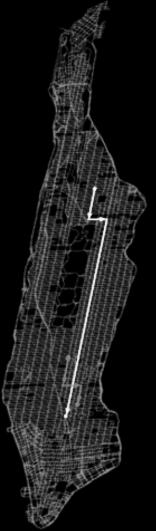


 $\Delta = 60 \text{ sec}$

More tolerance = denser network = more sharing opportunities

Krings et al, EPJ Data Sci 1 (2012)

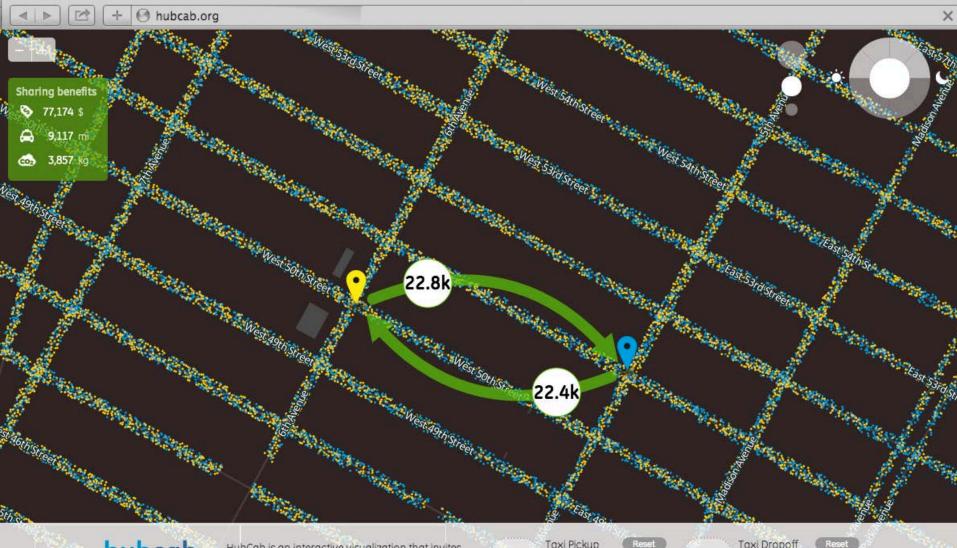






Learn more about the project $\ \downarrow$

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HubCab is an interactive visualization that invites you to explore the ways in which over 170 million taxi trips connect the City of New York in a given YEAF. Show me how it works.

Taxi Pickup West 50th Street

Total Pickups: 724 Average duration: 11.4 min Average distance: 2.64 mi

Taxi Dropoff

West 51st Street

Total Dropoffs: 1704 Average duration: 10.8 min Average distance: 2.06 mi

Learn more about the project $~~\downarrow~$

light traffic

Light Traffic

Improving traffic efficiency through slot-based intersections

SENSEABLE CITY LAB :..:



Pli

DriverlessCities: enablers

Communication technology

cellular and short-range radio technology can be used for V2V and V2I communication



Vehicle-smartphone integration



Short range radio communication

Self-driving vehicles

currently being tested in several cities worldwide and will soon become widespread



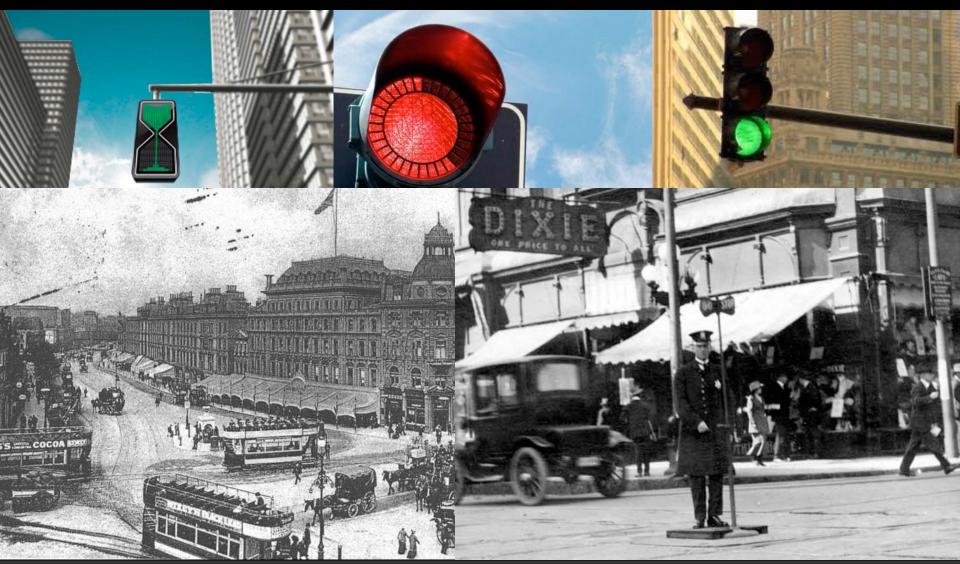
Google self driving car



Self driving technology

Traffic lights

Traffic lights are 150 years old technology, conceived for horses

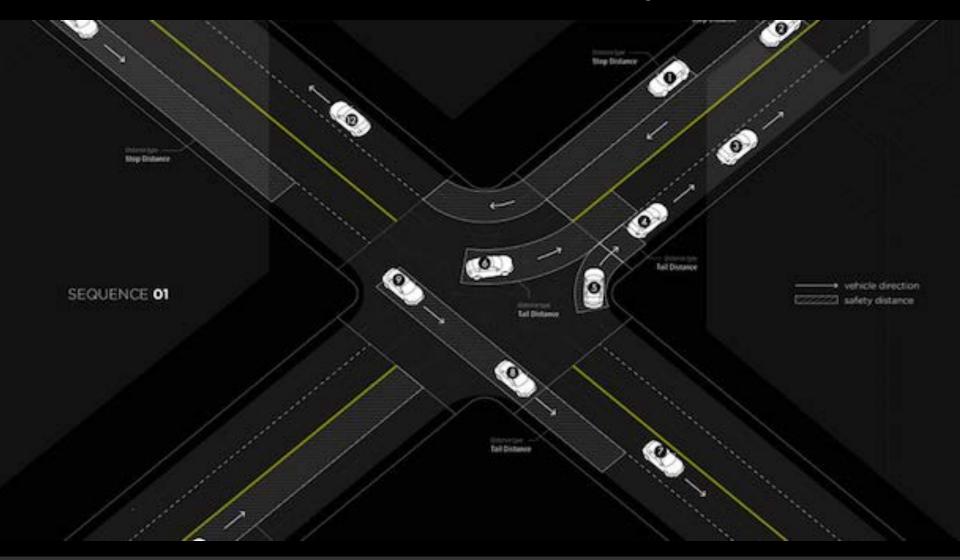


The death of traffic lights?

Driverless vehicles will just optimize traffic light operation (modern horses), or can we do something better?

Slot-based intersection

From flow-based to vehicle-based intersection management

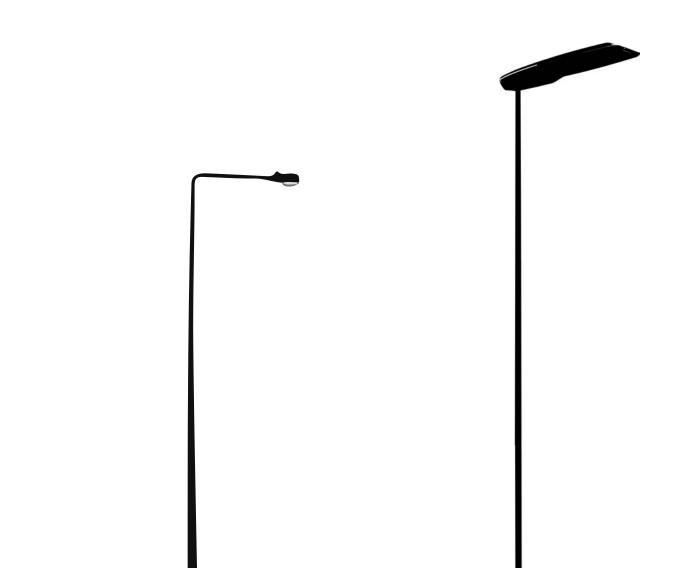


Light Traffic

Double intersection capacity vs. traffic light: with current traffic, queues would disappear

as above, so below

Let's talk about street lights



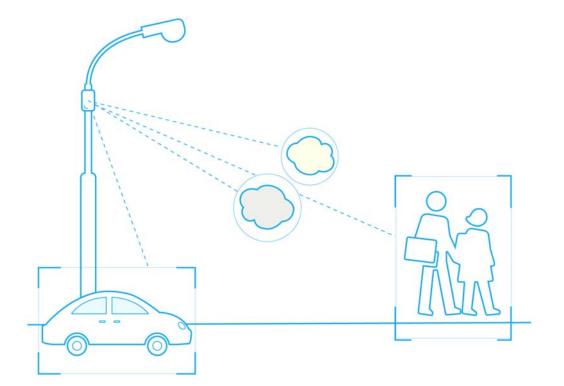
An <u>incredible</u> presence

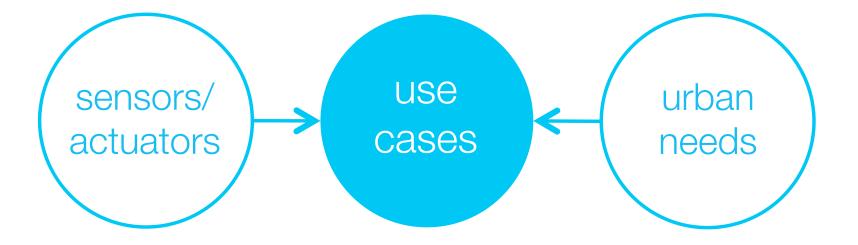
26 million streetlights in the United States

RESEARCH OBJECTIVE 1

Transform streetlights into an urban knowledge platform that senses the urban space.

Embed cheap, scalable sensors to provide insights into areas of difficult measurement about cities.

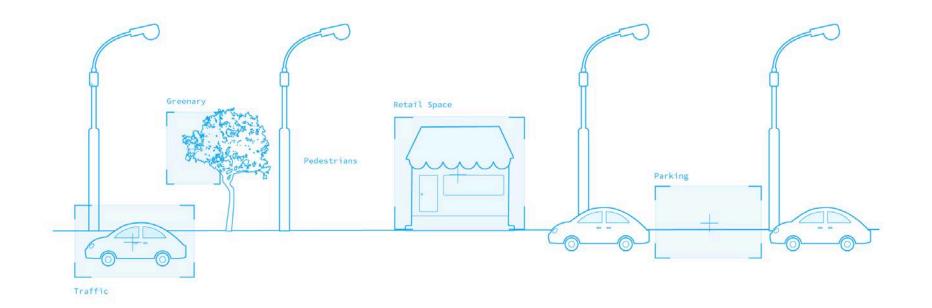






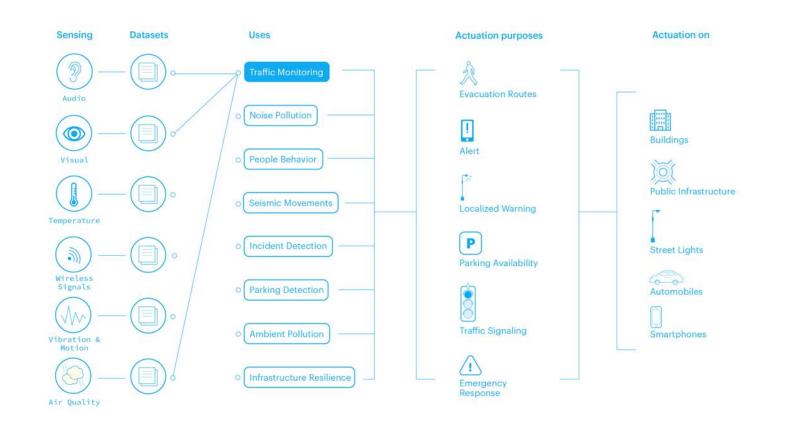
IIII SENSEABLE CITY LAB

ONE SENSOR, MULTIPLE <u>APPLICATIONS</u>



COMBINING SENSORS

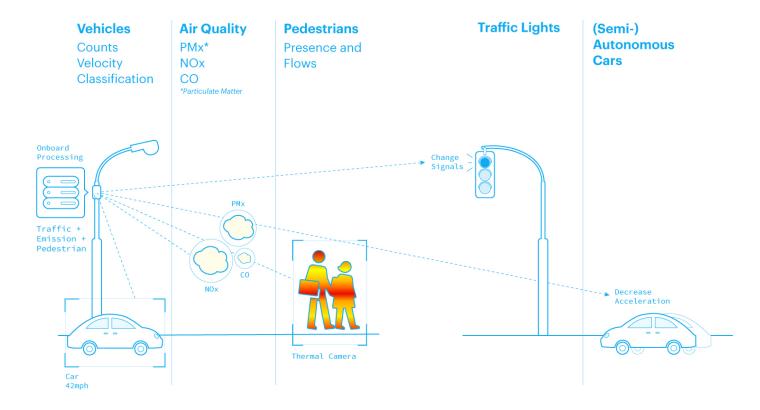
Ideation



Create a human centric and environmentally friendly street crossing integrating automated actuation cycles in traffic lights using real-time data from air quality and image sensors placed in streetlights.

1. Sensing and Processing

2. Actuation

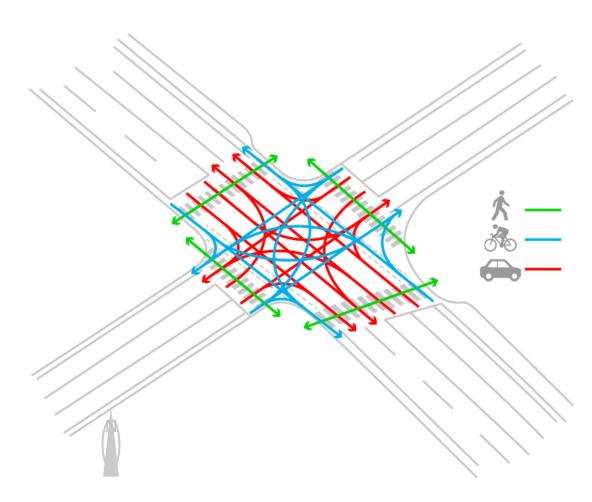


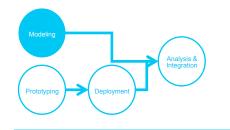
IIIT SENSEABLE CITY LAB :..:

STREET CROSSING

Flows directionality on Mass. Ave. & Vassar St.

- Complex environment
- Simultaneous mobility of automobiles, bicycles and pedestrians
- 34 possible directions of discrete flows
- 8 for pedestrians
- 12 for bicycles
- 14 for automobiles

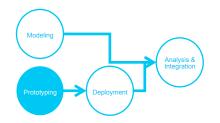


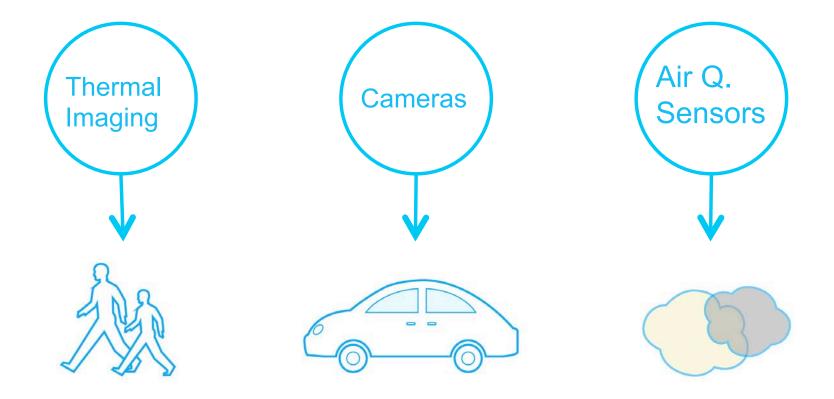


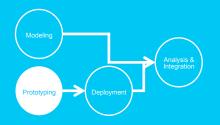
Traffic model of intersection

Loading the Model...

III SENSEABLE CITY LAB :..:





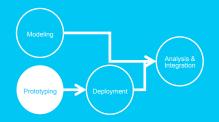


PROTOTYPING

Networked cameras & Hyper spectral Imaging

- Networked camera system (Wi-Fi 2.4 GHz)
- Cloud based trigger and synchronization control
- Low cost on board computer (RPi 2/3 based)
- Image sensor (5MP sensor programmable resolution and frame rate / 1080p 30fps video capable)
- Pi NOIR Infrared image sensor (5MP sensor)
- FLIR Lepton Thermal sensor (80 x 60 px)



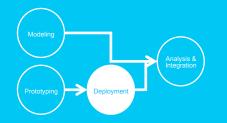


PROTOTYPING

Air Quality Nodes

- Gas phase pollutant concentrations: CO, NO, NO2, O3 + NO2) and CO2.
- Size-resolved particulate matter with estimated PM1, PM2.5, and PM10.
- Additional measurements: Barometric pressure, noise, ambient light intensity, wind speed, wind direction, relative humidity, and temperature

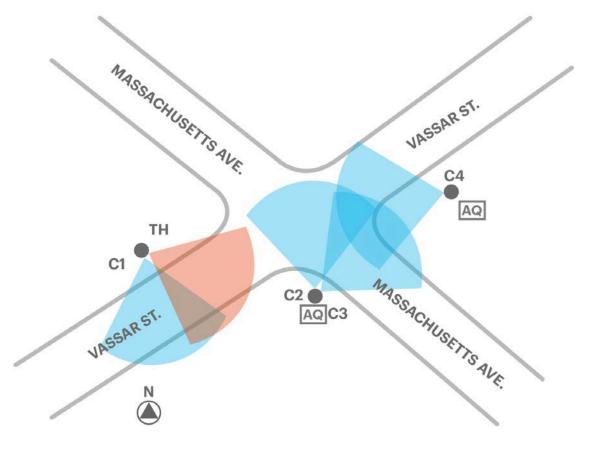


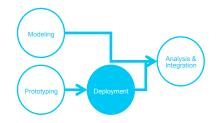


SENSOR DEPLOYMENT & DATA COLLECTION

Corner of Mass. Ave. & Vassar St.

- Synchronized data acquisition from multiple sensors
- Continuous data acquisition for A.Q. sensor nodes (one minute frequency sampling).
- Batch data sampling for video (1600x1200 px/15 FPS/H.264) for 15 min-2hr distributed periods throughout the day.
- Batch data sampling for thermal sensor (80x60px/2-20 FPS





PRIMARY DATA SAMPLING

Thermal and image sensors

Thermal sensor

2016-06-16 11:26:00

Camera 4



Camera 2



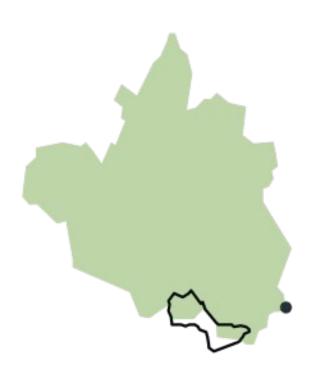
UNDERWORLDS



WHAT IS IN OUR COLLECTIVE GUT?







600,000 people 8+ hours travel time

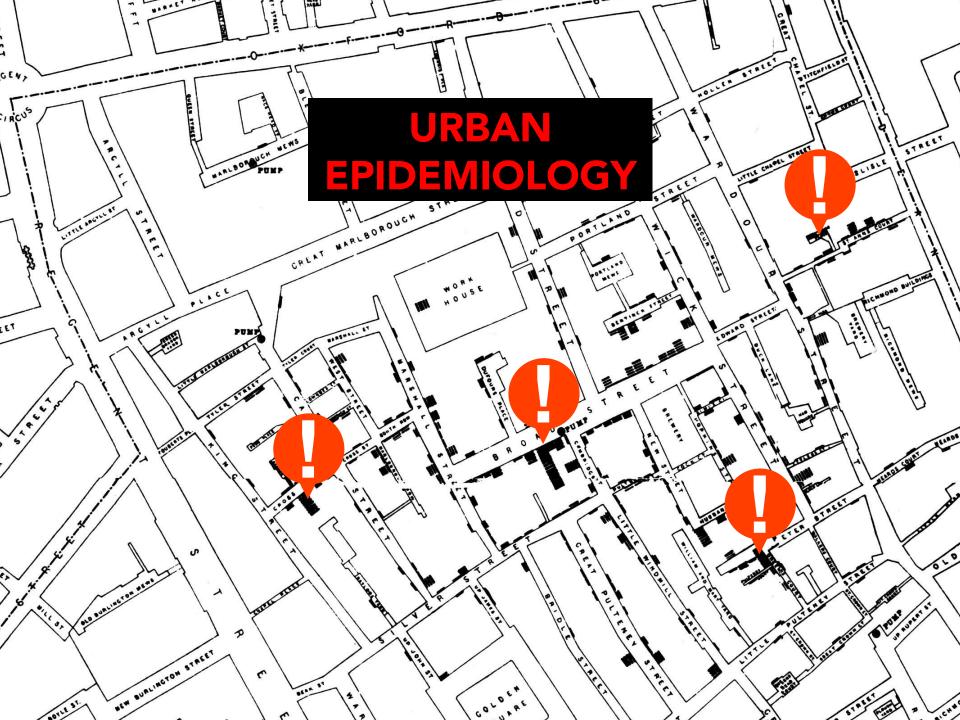


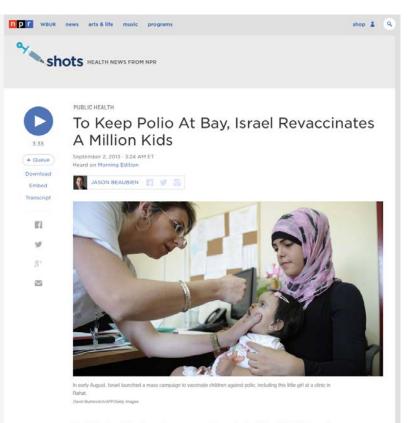
15 minutes travel time

HUMAN GUT MICROBIOME SIGNATURE



REAL-TIME DETECTION



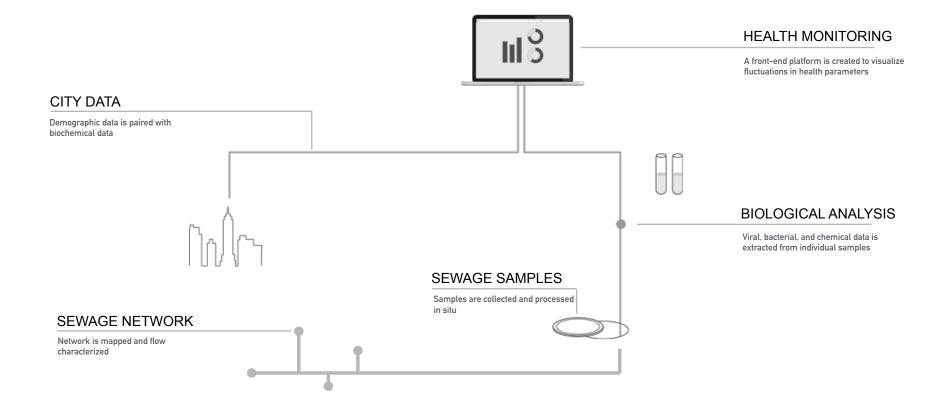


Israel is in the midst of a massive, emergency immunization drive of all children under the age of 9 against polio.

Why?

Health workers detected the virus in southern Israel in February. Since then, they've found it in 85 different sewage samples across the country, the Global Polio Eradication Initiative said Wednesday. Yet so far, no children have gotten sick or been paralyzed by the virus.

MULTISTEP PROJECT DEVELOPMENT



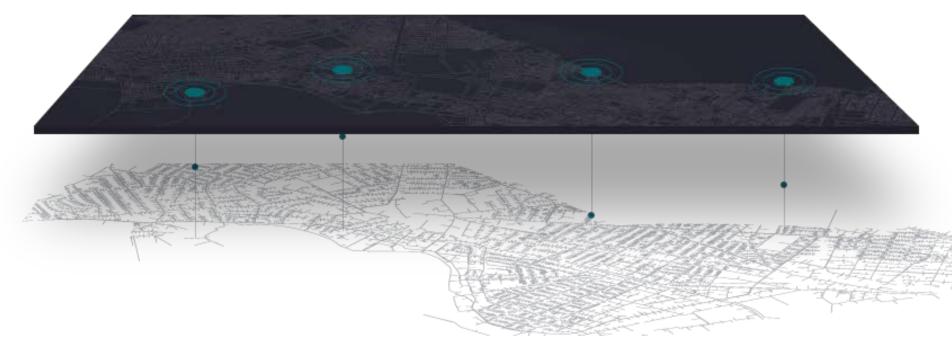
WHAT ARE WE LOOKING FOR?

A combination of discovery-mode (untargeted) and targeted protocols:

VIRUSES: REAL-TIME DISEASE TRACKING (human viral pathogen qPCR assays)

BACTERIA: MICROBIOME, ANTIBIOTIC RESISTANCE (16S and WGSS sequencing)

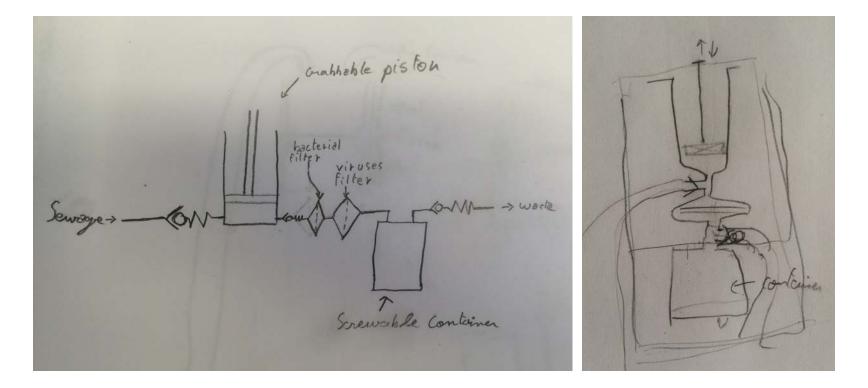
CHEMICALS: DETECTION, POLICY EVALUATION (mass spec & targeted metabolomics)



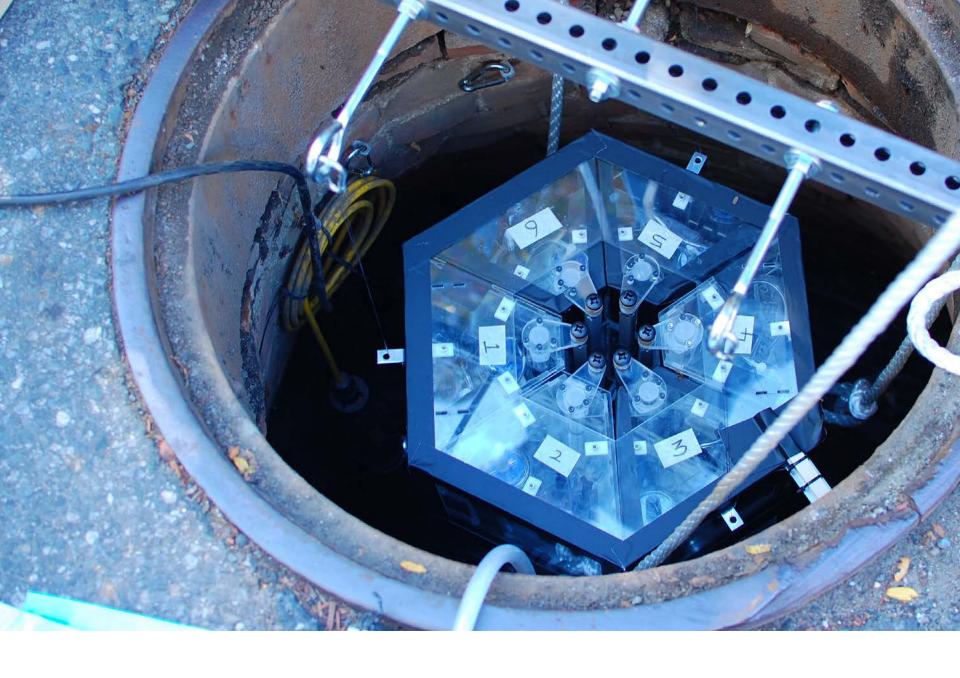




PROTOTYPING A NETWORK OF AUTOMATED SAMPLING INSTRUMENTS That are dynamically operated and sense information in situ









LUIGI



completed:

MECHANICAL

- cable coil
- geared DC motor
- peristaltic pump

ELECTRICAL

- micro-controller & battery
- fluid counter
- infrared distance sensor

FLUID

- preprocessing filter
- collection bottle
- intake & outtake tubing



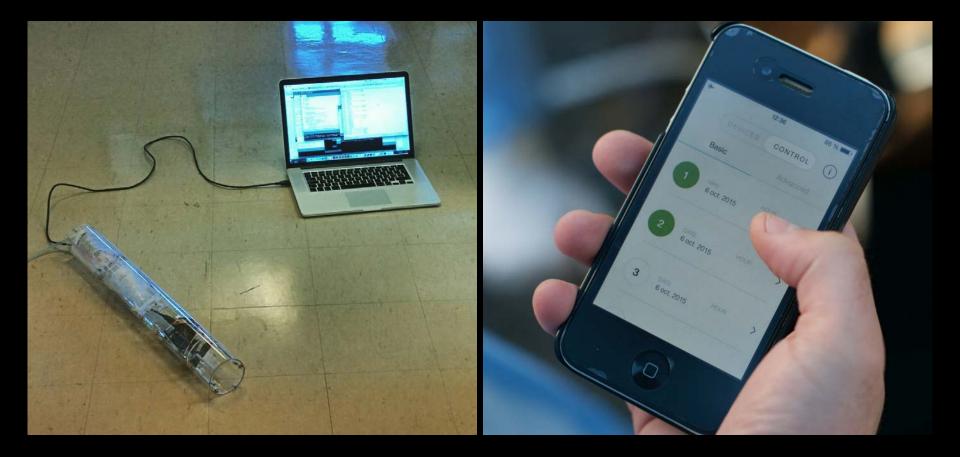
in progress:

SENSORS

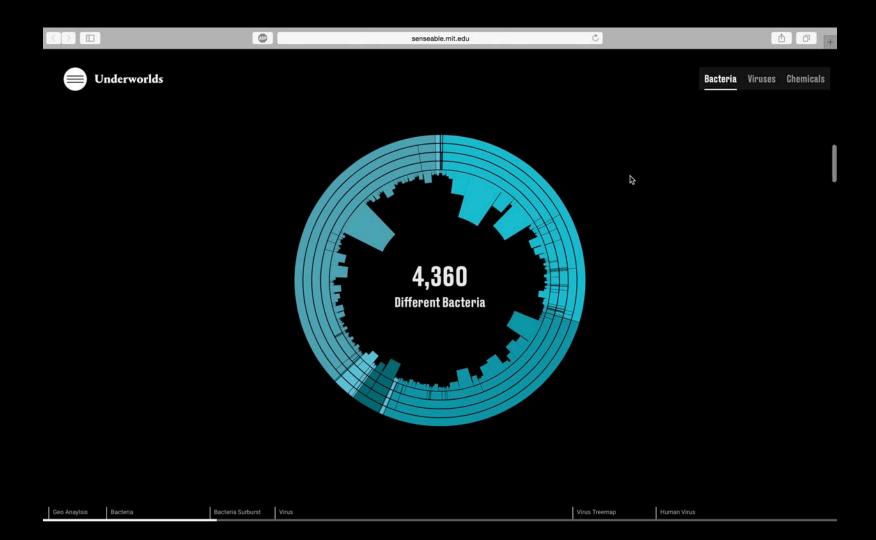
- temperature
- flow
- water & moisture
- microfluidics device
- targeted bio sensors

COMMUNICATION

- data collection and storage
- preprogrammed deployment



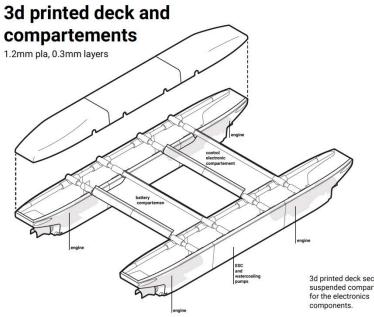




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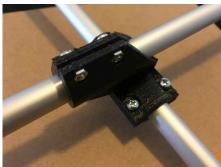
roboat prototyping



3d printed deck sections, suspended compartments

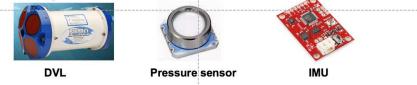






ASV, technology overview

- > GPS (Global Positioning System)
- > Doppler Velocity Logger (DVL): an instrument that measures the vehicle's relative velocity according to the Doppler effect.
- > Pressure sensor: estimate the surrounding flow conditions.
- > Inertial Measurement Unit (IMU): measures the robot attitude (yaw, pitch and roll), and the angular velocities.



For our roboat that requires docking and self-assembly, only GPS-based navigation is insufficient, vision-based localization system or Inertial Navigation System should be developed.

urban research and data





launch event

senseable city lab:.:: Massachusetts



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